

# ALCF Data and Learning Frameworks

J. Taylor Childers ALCF

## Data & Learning at the ALCF



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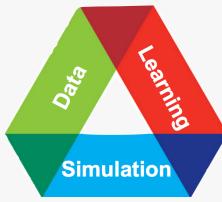
Jin Li



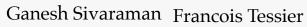
Alvaro Vazquez Mayagoitia



Adrian Pope

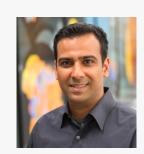




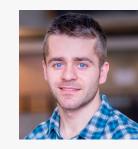




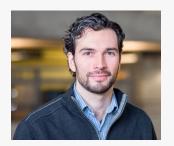
Tom Uram



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Data & Learning Frameworks for Theta

- Deep Learning:
  - Tensorflow+Keras
  - Horovod
  - Cray ML Plugin for Deep Learning
- Data Handling:
  - Spark
  - Singularity
  - Globus
  - RAM-disk (/tmp)
  - SSDs (Rick's talk)



## Deep Learning on Theta

- Support at ALCF has been focused on Tensorflow with the optional Keras API
- Intel offers an optimized Tensorflow wheel
- <u>Using Horovod</u> for scaling across nodes using data parallelism
- We have two supported Tensorflow installs:
  - Conda environment using Intel Tensorflow Wheel
  - Cray optimized ML plugin
- Both options have methods for running data-parallel training on Theta
  - Data-parallel means each node has a full ML model and trains on mini-batches of input data
  - After gradients are calculated locally, an ALLREDUCE is performed to compute a global gradient and synchronize the model parameters across nodes











#### **Tensorflow Installations: Conda Environment**

- A Conda environment is available and can be loaded using the **module load** command
  - module load miniconda-3.6/conda-4.4.10 (python 3.6)
  - module load miniconda-2.7/conda-4.4.10 (python 2.7)
  - Can query the local packages installed using conda list
  - Uses Intel optimized backends such as numpy and scipy to provide better performance
  - Tensorflow installed via Intel Wheel
  - Documented here: <a href="https://www.alcf.anl.gov/user-guides/conda">https://www.alcf.anl.gov/user-guides/conda</a>
- Use it this way:

```
#!/bin/bash
#COBALT -n <num-nodes>
#COBALT -t <wall-time>
#COBALT -q <queue>
#COBALT -A <project>

module load miniconda-3.6/conda-4.4.10

aprun -n <num-ranks> -N <mpi-ranks-per-node> python script.py
```



#### **Tensorflow Installations: Conda Environment**

- If you need to install custom modules you can clone the installation
- Be aware that the Conda installations have the Cray MPI libs copied into their ./lib areas to ensure compatibility with Theta

conda create -p /path/to/new/env --clone /soft/datascience/conda/miniconda3/4.4.10

• This will clone the installation to your own area.

source activate /path/to/new/env

- Then you can install other python modules using
  - -conda install
  - -pip install
- Removing the **--clone** would provide you with a clean environment with nothing installed.



#### **Tensorflow Installations: Conda Environment**

• Using this in a submit script

```
#!/bin/bash
#COBALT -n <num-nodes>
#COBALT -t <wall-time>
#COBALT -q <queue>
#COBALT -A <project>

module load miniconda-3.6/conda-4.4.10
source activate /path/to/new/env
aprun -n <num-ranks> -N <mpi-ranks-per-node> python script.py
```



## Tensorflow Installations: Cray Plugin

- More details in Peter Mendygral's Slides
- Communication plugin with Python and C APIs
- Optimized for TensorFlow but also portable to other frameworks
  - Callable from C/C++ source
  - Called from Python if data stored in NumPy arrays or Tensors
- Like Horovod does not require modification to TensorFlow source
  - User modifies training script
- Uses custom ALLREDUCE specifically optimized for DL workloads
  - Optimized for Cray Aries interconnect and IB for Cray clusters
- Tunable through API and environment variables
- Supports multiple gradient aggregations at once with thread teams
  - Useful for Generative Adversarial Networks (GAN), for example
- Example submit scripts here:

/lus/theta-fs0/projects/SDL\_Workshop/mendygra/cpe\_plugin\_py2.batch /lus/theta-fs0/projects/SDL\_Workshop/mendygra/cpe\_plugin\_py3.batch





## Tensorflow Installations: Cray Plugin

- The Cray Python environment can be loaded via
- Environment setup for Python 2.7:

```
module load cray-python
export PYTHONUSERBASE=/lus/theta-fs0/projects/SDL_Workshop/mendygra/pylibs
module load /lus/theta-fs0/projects/SDL_Workshop/mendygra/tmp_inst/modulefiles/craype-ml-plugin-py2/1.1.0
```

• Environment setup for Python 3.6

```
module load cray-python/3.6.1.1
export PYTHONUSERBASE=/lus/theta-fs0/projects/SDL_Workshop/mendygra/pylibs
module load /lus/theta-fs0/projects/SDL_Workshop/mendygra/tmp_inst/modulefiles/craype-ml-plugin-py3/1.1.0
```



#### **Environment Customizations for Theta**

```
#!/bin/bash
#COBALT -n <num-nodes>
#COBALT -t <wall-time>
#COBALT -q <queue>
# load your environment
module load ...
# from Peter Mendygral
# Specifies the number of threads to use.
OMP NUM THREADS=62
# milliseconds a thread waits after completing
# the execution of a parallel region, before sleeping.
KMP BLOCKTIME=0 # 30 sometimes good too
# Enables the run-time library to bind threads to physical processing units.
KMP AFFINITY="granularity=fine,compact,1,0"
aprun -n <num-ranks> -N <mpi-ranks-per-node> python script.py
```

- Submit script should include the environment variables below
- Some insight into these settings is here: <a href="https://www.tensorflow.org/performance/performance\_guide">https://www.tensorflow.org/performance\_guide</a>



#### **Environment Customizations for Theta**

- In general, you can play with the Tensorflow configuration for threading to optimize performance
  - intra\_op\_parallelism\_threads: Setting this equal to the number of physical cores is recommended. Setting the value to 0, which is the default and will result in the value being set to the number of logical cores, is an option to try for some architectures. This value and OMP\_NUM\_THREADS should be equal.
  - inter\_op\_parallelism\_threads: Setting this equal to the number of sockets is recommended. Setting the value to 0, which is the default, results in the value being set to the number of logical cores.
- There is an example TF CNN implementation which implements these via command line flags here:
  - https://github.com/tensorflow/benchmarks/blob/ mkl\_experiment/scripts/tf\_cnn\_benchmarks/ tf\_cnn\_benchmarks.py



#### **Environment Customizations for Theta**

- configuration for th
  - intra\_op\_paralle number of physical ( which is the default number of logical cor This value and OMP

```
• In general, you def create_config_proto():
                      config = tf.ConfigProto()
                      config.allow soft placement = True
                      config.intra op parallelism threads = FLAGS.num intra threads
                      config.inter op parallelism threads = FLAGS.num inter threads
                      config.gpu_options.force_gpu_compatible = FLAGS.force gpu compatible
                      #config.graph options.rewrite options.disable model pruning = True
                      return config
```

protocol=FLAGS.server\_protocol)

- inter\_op\_paralle\_ number of sockets is recommended. Setting the value to 0, which is the default, results in self.server = tf.train.Server(self.cluster, job\_name=self.job\_name, task\_index=self.task\_index, cores. config=create\_config\_proto(),
- There is an examp implements these via command time mags nere.
  - https://github.com/tensorflow/benchmarks/blob/ mkl\_experiment/scripts/tf\_cnn\_benchmarks/ tf\_cnn\_benchmarks.py



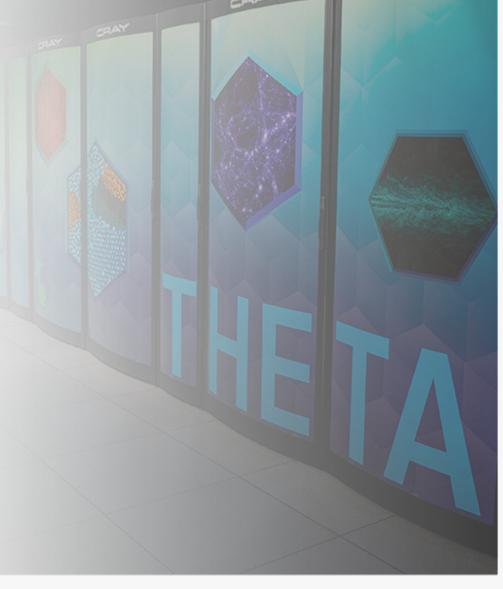
## Filesystem Customizations for Theta

- Use Lustre striping to improve filesystem performance during training
- First create a directory that will be striped across multiple Lustre sources

```
lfs setstripe —c 16 [samples directory]
```

• Then copy the input files into this directory

```
cp [dataset files] [samples directory]
```



- https://github.com/uber/horovod
- Horovod is part of the Conda environment when setup
- Horovod is a simple wrapper using MPI to synchronize gradients prior to updating model parameters
- It has support for native Tensorflow or Keras with Tensorflow as the backend







```
import keras
# ...
import horovod.keras as hvd
# Horovod: initialize Horovod.
hvd.init()
#... data loading, etc. ....
# create model
model = Sequential()
model.add(Conv2D(32, kernel size=(3, 3),activation='relu',input shape=input shape))
# ...
# create optimizer
opt = keras.optimizers.Adadelta()
# wrap with Horovod Distributed Optimizer
opt = hvd.DistributedOptimizer(opt)
# pass horovod optimizer instead of keras optimizer to model compilation step
model.compile(loss=keras.losses.categorical crossentropy,
              optimizer=opt,
              metrics=['accuracy'])
model.fit(x train, y train,
          batch size=batch size,
          callbacks=callbacks,
          epochs=epochs,
          verbose=1,
          validation data=(x test, y test))
```







- Easiest implementation using Keras + Tensorflow
- For Keras one can simply add the code above

• In the case of Keras, one can set the Tensorflow threading options in this way.







- Horovod can also be added to a native Tensorflow training script
- <a href="https://github.com/uber/horovod/blob/master/examples/tensorflow\_mnist.py">https://github.com/uber/horovod/blob/master/examples/tensorflow\_mnist.py</a>
- This requires a few more edits

```
import tensorflow as tf
import horovod.tensorflow as hvd
# . . . helper functions . . .
def main(_):
    # Horovod: initialize Horovod.
    hvd.init()
    # Download and load MNIST dataset.
    mnist = learn.datasets.mnist.read_data_sets('MNIST-data-%d' % hvd.rank())
    # . . . build model . . .
    # Horovod: adjust learning rate based on number of GPUs.
    opt = tf.train.RMSPropOptimizer(0.001 * hvd.size())
    # Horovod: add Horovod Distributed Optimizer.
    opt = hvd.DistributedOptimizer(opt)
    # . . . build train_op . . .
```

- Horc
- https
- This

```
hooks = |
   # Horovod: BroadcastGlobalVariablesHook broadcasts initial variable states
   # from rank 0 to all other processes. This is necessary to ensure consistent
    # initialization of all workers when training is started with random weights
   # or restored from a checkpoint.
    hvd.BroadcastGlobalVariablesHook(0),
   # Horovod: adjust number of steps based on number of nodes.
   tf.train.StopAtStepHook(last step=20000 // hvd.size()),
   tf.train.LoggingTensorHook(tensors={'step': global step, 'loss': loss},
                               every n iter=10),
# Horovod: save checkpoints only on worker 0 to prevent other workers from
# corrupting them.
checkpoint dir = './checkpoints' if hvd.rank() == 0 else None
# The MonitoredTrainingSession takes care of session initialization,
# restoring from a checkpoint, saving to a checkpoint, and closing when done
# or an error occurs.
with tf.train.MonitoredTrainingSession(checkpoint dir=checkpoint dir,
                                       hooks=hooks,
                                       config=config) as mon sess:
   while not mon sess.should stop():
        # Run a training step synchronously.
        image , label = mnist.train.next batch(100)
        mon sess.run(train op, feed dict={image: image , label: label })
```

nist.py

- After **module load** setup from Slide 9
- See some example scripts:

```
less $CRAYPE_ML_PLUGIN_BASEDIR/examples/tf_mnist/mnist.py
```

• Import the Cray plugin in your code:

```
import tensorflow as tf
# load Cray plugin
import ml_comm as mc
# ...
```

- Must tell the Cray plugin the number of trainable parameters in your model for memory alloc
- This is the initialization step

• This is the finalization step

```
# CRAY ADDED
if FLAGS.enable_ml_comm:
    mc.finalize()
# END CRAY ADDED
```

• Update Optimizer to synchronize gradients and apply

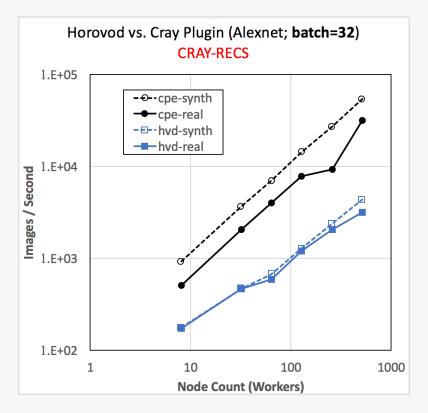
• Additional initialization:

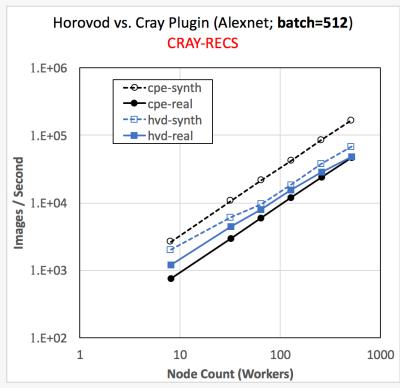
```
# CRAY ADDED
# since this script uses a monitored session, we need to create a hook to initialize
# variables after the session is generated
class BcastTensors(tf.train.SessionRunHook):
  def init (self):
    self.bcast = None
  def begin(self):
    if not self.bcast:
      new vars = mc.broadcast(tf.trainable variables(),0)
      self.bcast = tf.group(*[tf.assign(v,new vars[k]) for k,v in enumerate(tf.trainable variables())])
  def after create session(self, session, coord):
     session.run(self.bcast)
     if FLAGS.ml comm validate init:
       py all vars = [session.run(v) for v in tf.trainable variables()]
       if (mc.check buffers match(py all vars,1) != 0):
         print("ERROR: not all processes have the same initial model!")
       else:
         print("Initial model is consistent on all ranks")
# END CRAY ADDED
```

• Additional initialization:

```
# CRAY ADDED
# since this script uses a monitored session, we need to create a hook to initialize
# variables after the session is generated
class BcastTensors(tf.train.SessionRunHook)
                                             # CRAY ADDED
                                             # add to our list of session hooks for the initial bcast of the model
  def init (self):
                                             sess hooks = []
    self.bcast = None
                                             if FLAGS.enable ml comm:
                                               sess hooks = [BcastTensors()]
  def begin(self):
                                             # END CRAY ADDED
    if not self.bcast:
      new_vars = mc.broadcast(tf.trainabl tf.estimator.EstimatorSpec(
                                                   mode=mode,
      self.bcast = tf.group(*[tf.assign(v,n]
                                                   predictions=predictions,
                                                   loss=loss,
  def after create session(self, session, c
                                                   train op=train op,
     session.run(self.bcast)
                                                   training hooks=sess hooks,
                                                   eval metric ops=metrics)
     if FLAGS.ml comm validate init:
       py all vars = [session.run(v) for v in tf.trainable variables()]
       if (mc.check buffers match(py all vars,1) != 0):
         print("ERROR: not all processes have the same initial model!")
       else:
         print("Initial model is consistent on all ranks")
# END CRAY ADDED
```

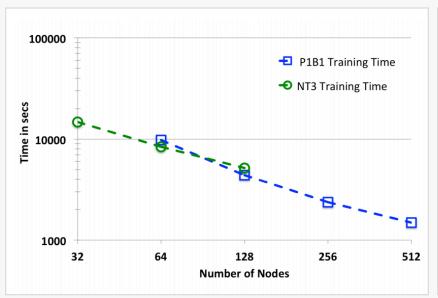
## Cray Vs. Horovod Performance

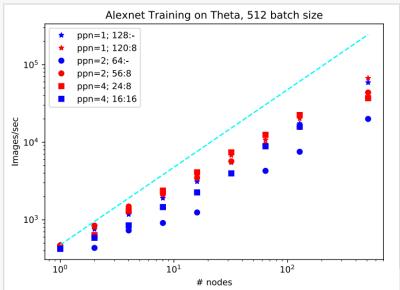




- Scaling results comparing Horovod+TF in Conda vs Cray ML Plugin
- Images processed per second
- Left uses local mini-batch size of 32
- **Right** uses local mini-batch size of 512
- Cray plugin outperforms Horovod in the highcommunication region.

#### Some Horovod Performance Measures





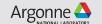
• A nice example script is located here which abstracts all the features described and more:

/projects/datascience/elise/helper\_scripts/tf\_wrapper.py

• Example batch script using this is here:

/projects/datascience/elise/TF\_alexnet.sh

- On the Left
- Testing with Horovod+TF using data parallel training
- Scaled data-parallel training for two Candle benchmarks to 512 nodes on Theta
- On the Right
- Alexnet training example using different numbers of processes per node (ppn) and total node count
- Inter/Intra Op Thread settings varied as well.
- Shows near linear strong scaling



## **Monitoring With Tensorboard**

• You can monitor training variables using Tensorboard on Theta

```
module load miniconda-3.6/conda-4.4.10
tensorboard --logdir </path/to/checkpointdir>
```

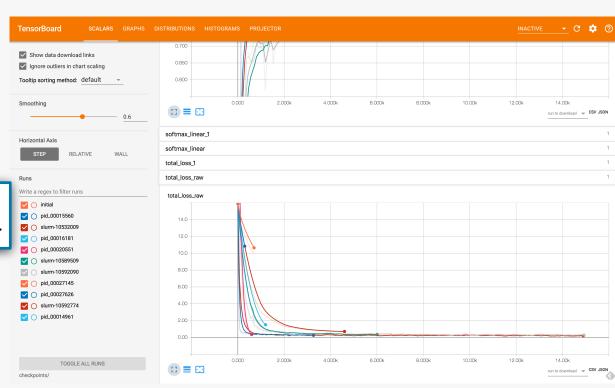
After it starts you will see something like this

```
TensorBoard 1.6.0 at http://thetalogin5:6006
(Press CTRL+C to quit)
```

• You can connect by port forwarding when you login to Theta:

```
ssh -D <some-high-port-number> <a href="mailto:theta.alcf.anl.gov">theta.alcf.anl.gov</a>
```

- On your laptop, in Firefox, you can set the browser to use a socks5 proxy 'localhost' with the same port number you used above
- Then enter **thetalogin5:6006** as the url



## Running Spark on Theta



- What is Spark?
  - Method for data-parallel applications to scale easily on HPCs
- Installed on Theta, can run your Spark-enabled applications using this recipe:

- Still working on documentation on website and standardizing the installation on Theta
- Currently benchmarking to understand proper configurations and use-cases



## Containers on Theta with Singularity

- We use Singularity due to the rights escalation issue in Docker
- https://www.alcf.anl.gov/user-guides/singularity
- Available on Theta login nodes for downloading images
- Images can be built using

```
singularity build myubuntu.img docker://ubuntu
singularity build myubuntu.img <a href="mailto:shub://singularityhub/ubuntu">shub://singularityhub/ubuntu</a>
singularity build myubuntu.img docker://jtchilders/mpitest:latest
```

- Generally the Singularity build command requires 'sudo' rights to run except in these cases where you have an image already on a HUB
- The following instructions show how to build an Singularity container on the Singularity Hub

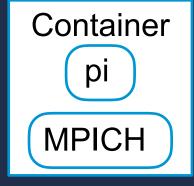


http://singularity.lbl.gov/

## Overview of the Workflow in Five Easy Steps!

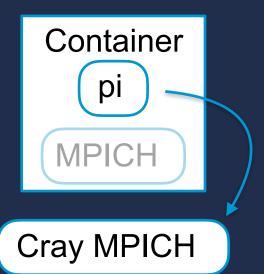
- 1. Create SingularityFile recipe in github
- 2. Link repo to Singularity Hub
- 3. Wait for build
- 4. Build on Theta
- 5. Run on Theta

## **Built on Singularity Hub**





#### **Run on Theta**



## Singularity Usage on Theta

- Building containers from Scratch
- Create a Singularity recipe file

```
Bootstrap: docker
     From: centos
    %setup
       echo ${SINGULARITY_R00TFS}
       mkdir ${SINGULARITY_ROOTFS}/myapp
       cp pi.c ${SINGULARITY_ROOTFS}/myapp/
 9
    %post
10
       yum update -y
       yum groupinstall -y "Development Tools"
       yum install —y gcc
       yum install -y gcc-c++
       yum install -y wget
       cd /myapp
       # install MPICH
       wget http://www.mpich.org/static/downloads/3.2.1/mpich-3.2.1.tar.gz
       tar xf mpich-3.2.1.tar.gz
       cd mpich-3.2.1
       # disable the addition of the RPATH to compiled executables
       # this allows us to override the MPI libraries to use those
22
       # found via LD_LIBRARY_PATH
        ./configure --prefix=$PWD/install --disable-wrapper-rpath
24
       make -j 4 install
       # add to local environment to build pi.c
       export PATH=$PATH:$PWD/install/bin
       export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$PWD/install/lib
       cd ..
       mpicc -o pi -fPIC pi.c
30
    %runscript
```

/myapp/pi



Bootstrap: docker

```
From: centos
    %setup
       echo ${SINGULARITY_R00TFS}
       mkdir ${SINGULARITY_ROOTFS}/myapp
       cp pi.c ${SINGULARITY_ROOTFS}/myapp/
 9
    %post
10
       yum update -y
       yum groupinstall -y "Development Tools"
       yum install —y gcc
       yum install -y gcc-c++
       yum install -y wget
       cd /myapp
       # install MPICH
16
       wget http://www.mpich.org/static/downloads/3.2.1/mpich-3.2.1.tar.gz
18
       tar xf mpich-3.2.1.tar.gz
19
       cd mpich-3.2.1
       # disable the addition of the RPATH to compiled executables
       # this allows us to override the MPI libraries to use those
22
       # found via LD_LIBRARY_PATH
23
        ./configure --prefix=$PWD/install --disable-wrapper-rpath
24
       make -j 4 install
       # add to local environment to build pi.c
       export PATH=$PATH:$PWD/install/bin
       export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$PWD/install/lib
28
       cd ..
29
       mpicc -o pi -fPIC pi.c
30
    %runscript
       /myapp/pi
```

Make working directory. Copy files from into image.

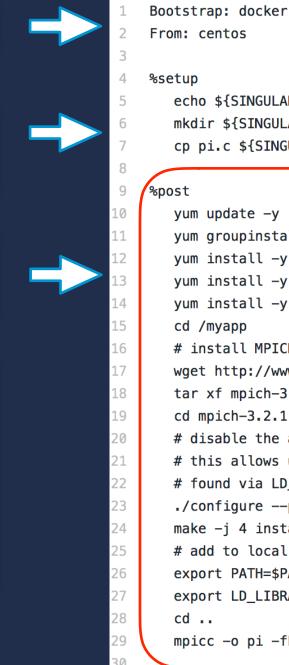
During the 'setup' phase, the image does not yet exist and is still on the host filesystem at the path SINGULARITY\_ROOTFS
This creates app directory at '/myapp' in the image

```
Bootstrap: docker
    From: centos
    %setup
       echo ${SINGULARITY_R00TFS}
       mkdir ${SINGULARITY_ROOTFS}/myapp
       cp pi.c ${SINGULARITY_ROOTFS}/myapp/
    %post
       yum update -y
       yum groupinstall -y "Development Tools"
       yum install —y gcc
       yum install -y gcc-c++
       yum install -y wget
       cd /myapp
       # install MPICH
       wget http://www.mpich.org/static/downloads/3.2.1/mpich-3.2.1.tar.gz
       tar xf mpich-3.2.1.tar.qz
       cd mpich-3.2.1
       # disable the addition of the RPATH to compiled executables
       # this allows us to override the MPI libraries to use those
       # found via LD_LIBRARY_PATH
       ./configure --prefix=$PWD/install --disable-wrapper-rpath
24
       make -j 4 install
       # add to local environment to build pi.c
       export PATH=$PATH:$PWD/install/bin
       export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$PWD/install/lib
       cd ..
       mpicc -o pi -fPIC pi.c
    %runscript
       /myapp/pi
```

Make working directory. Copy files from into image.

Commands to install my image with the application.

Install via 'yum' any packages needed to build application inside the container. Build MPICH by hand, then builds application.



```
From: centos
%setup
  echo ${SINGULARITY_R00TFS}
  mkdir ${SINGULARITY_ROOTFS}/myapp
  cp pi.c ${SINGULARITY_ROOTFS}/myapp/
%post
  yum update -y
  yum groupinstall -y "Development Tools"
  yum install —y gcc
  yum install -y gcc-c++
  yum install -y wget
  cd /myapp
  # install MPICH
  wget http://www.mpich.org/static/downloads/3.2.1/mpich-3.2.1.tar.gz
  tar xf mpich-3.2.1.tar.qz
  cd mpich-3.2.1
  # disable the addition of the RPATH to compiled executables
  # this allows us to override the MPI libraries to use those
  # found via LD_LIBRARY_PATH
   ./configure --prefix=$PWD/install --disable-wrapper-rpath
  make -j 4 install
  # add to local environment to build pi.c
  export PATH=$PATH:$PWD/install/bin
  export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$PWD/install/lib
  cd ..
  mpicc -o pi -fPIC pi.c
%runscript
  /myapp/pi
```

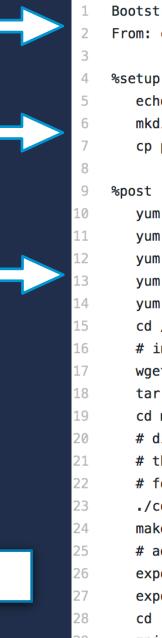
Make working directory. Copy files from into image.

Commands to install my image with the application.

Typically containers are built to run one executable.

singularity run myapp.img

Specify the executable to run with container is called



```
Bootstrap: docker
From: centos
  echo ${SINGULARITY_R00TFS}
  mkdir ${SINGULARITY_ROOTFS}/myapp
  cp pi.c ${SINGULARITY_ROOTFS}/myapp/
  yum update -y
  yum groupinstall -y "Development Tools"
  yum install —y gcc
  yum install -y gcc-c++
  yum install -y wget
  cd /myapp
  # install MPICH
  wget http://www.mpich.org/static/downloads/3.2.1/mpich-3.2.1.tar.gz
  tar xf mpich-3.2.1.tar.qz
  cd mpich-3.2.1
  # disable the addition of the RPATH to compiled executables
  # this allows us to override the MPI libraries to use those
  # found via LD_LIBRARY_PATH
   ./configure --prefix=$PWD/install --disable-wrapper-rpath
  make -j 4 install
  # add to local environment to build pi.c
  export PATH=$PATH:$PWD/install/bin
  export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$PWD/install/lib
  cd ..
  mpicc -o pi -fPIC pi.c
%runscript
   /myapp/pi
```

```
pi.c source is here: https://
www.alcf.anl.gov/user-guides/example-
program-and-makefile-bgq
```

It's a straightforward MPI application that calculates pi with MPI\_REDUCE.

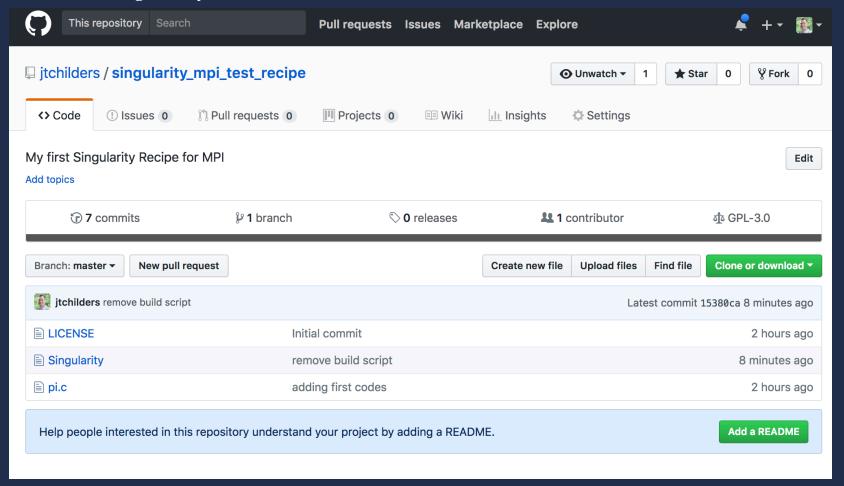
```
Bootstrap: docker
    From: centos
    %setup
       echo ${SINGULARITY_R00TFS}
       mkdir ${SINGULARITY_ROOTFS}/myapp
       cp pi.c ${SINGULARITY_ROOTFS}/myapp/
    %post
       yum update -y
       yum groupinstall -y "Development Tools"
       yum install —y gcc
       yum install -y gcc-c++
       yum install -y wget
       cd /myapp
       # install MPICH
       wget http://www.mpich.org/static/downloads/3.2.1/mpich-3.2.1.tar.gz
       tar xf mpich-3.2.1.tar.qz
       cd mpich-3.2.1
       # disable the addition of the RPATH to compiled executables
       # this allows us to override the MPI libraries to use those
22
       # found via LD_LIBRARY_PATH
       ./configure --prefix=$PWD/install --disable-wrapper-rpath
24
       make -j 4 install
       # add to local environment to build pi.c
       export PATH=$PATH:$PWD/install/bin
       export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$PWD/install/lib
       cd ..
       mpicc -o pi -fPIC pi.c
30
    %runscript
       /myapp/pi
```

```
wget http://www.mpich.org/static/downloads/3.2.1/mpich-3.2.1.tar.gz
tar xf mpich-3.2.1.tar.gz
cd mpich-3.2.1
./configure --prefix=$PWD/install --disable-wrapper-rpath
make -j 4 install
export PATH=$PATH:$PWD/install/bin
export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$PWD/install/lib
cd ..
mpicc -o pi -fPIC pi.c
```

- Notice manual installation of MPICH into container.
- The configure command disables the setting of RPATH during linking of the shared MPI libraries.
- After installation of MPICH, PATH & LD\_LIBRARY\_PATH are set to include MPICH
- Then pi is built
- IMPORTANT: ensure it dynamically (not statically) links against MPICH

#### Create new Github Repository

- <a href="https://github.com/jtchilders/singularity\_mpi\_test\_recipe">https://github.com/jtchilders/singularity\_mpi\_test\_recipe</a>
- Need to add recipe file inside with filename 'Singularity'
- Add file pi.c from previous link





- Goto: <a href="https://www.singularity-hub.org/login/">https://www.singularity-hub.org/login/</a>
- Authenticate using your Github account
- You can then add github repositories to your container collection.
- Click the big red button

•



My Container Collections

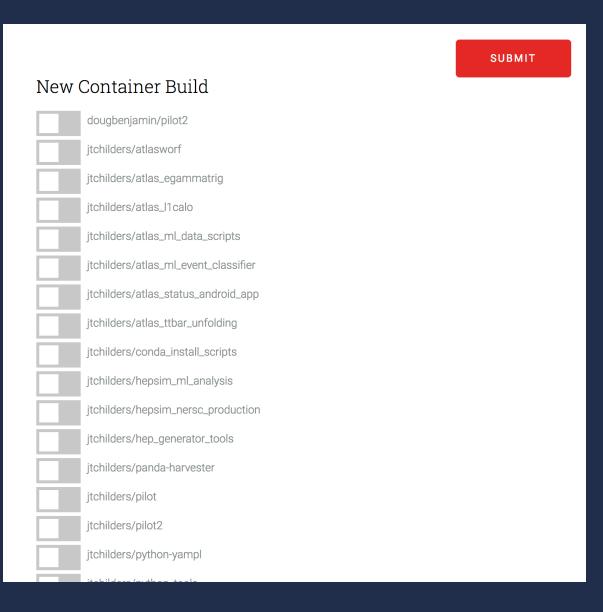
#### **ADD A COLLECTION**

One collection is created for each connected Github repository. In that collection, several containers master branch of the Github repository.

Read more about recipe file naming or build options.

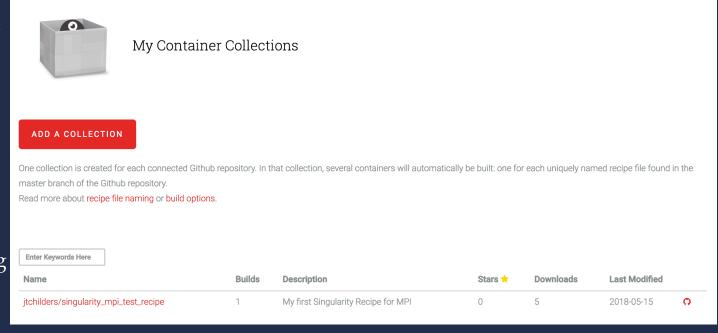
- Goto: <a href="https://www.singularity-hub.org/login/">https://www.singularity-hub.org/login/</a>
- Authenticate using your Github account
- You can then add github repositories to your container collection.
- Click the big red button
- Select your new repository and click the big red button

•

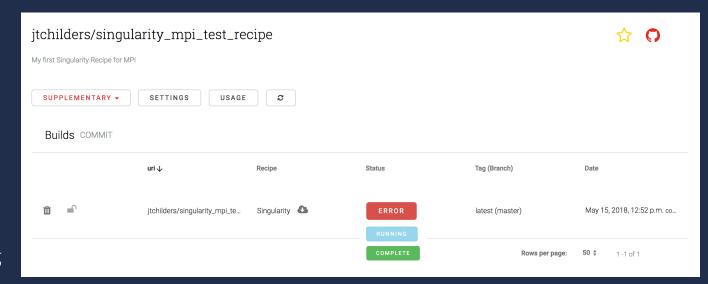




- Goto: <a href="https://www.singularity-hub.org/login/">https://www.singularity-hub.org/login/</a>
- Authenticate using your Github account
- You can then add github repositories to your container collection.
- Click the big red button
- Select your new repository and click the big red button
- Now you have your recipe listed and Singularity Hub will begin recursively searching the repo for any files named 'Singularity' and building those recipes
- Our example only has 1 recipe
- Click on the recipe



- Goto: <a href="https://www.singularity-hub.org/login/">https://www.singularity-hub.org/login/</a>
- Authenticate using your Github account
- You can then add github repositories to your container collection.
- Click the big red button
- Select your new repository and click the big red button
- Now you have your recipe listed and Singularity Hub will begin recursively searching the repo for any files named 'Singularity' and building those recipes
- Our example only has 1 recipe
- Click on the recipe to see it's build status
- Error messages during build can be seen by clicking the big red button
- Otherwise it will list the container as COMPLETE





### **Retrieving Container**

• Run the following on Theta to download and create an image:

singularity build myapp.img shub://jchilders/singularity\_mpi\_test\_recipe

# Running Singularity Container on Theta

qsub submit.sh



```
#!/bin/bash
#COBALT -t 30
#COBALT -q debuq-cache-quad
                                            Standard Cobalt parameters
#COBALT -n 2
#COBALT -A EnergyFEC 3
# app build with GNU not Intel
module swap PrgEnv-intel PrgEnv-gnu
# Use Cray's Application Binary Independent MPI build
module swap cray-mpich cray-mpich-abi
# prints to log file the list of modules loaded (just a check)
module list
# include CRAY LD LIBRARY PATH in to the system library path
export LD LIBRARY PATH=$CRAY LD LIBRARY PATH:$LD LIBRARY PATH
# also need this additional library
export LD LIBRARY PATH=/opt/cray/wlm detect/1.2.1-6.0.4.0 22.1 gd26a3dc.ari/lib64/:$LD LIBRARY PATH
# in order to pass environment variables to a Singularity container create the variable
# with the SINGULARITYENV prefix
export SINGULARITYENV LD LIBRARY PATH=$LD LIBRARY PATH
# print to log file for debug
echo $SINGULARITYENV LD LIBRARY PATH
# this simply runs the command 'ldd /myapp/pi' inside the container and should show that
# the app is running agains the host machines Cray libmpi.so not the one inside the container
aprun -n 1 -N 1 singularity exec -B /opt:/opt:ro -B /var/opt:/var/opt:ro mpitest.img ldd /myapp/pi
# run my contianer like an application, which will run '/myapp/pi'
aprun -n 8 -N 4 singularity run -B /opt:/opt:ro -B /var/opt:/var/opt:ro mpitest.img
```

```
#!/bin/bash
#COBALT -t 30
#COBALT -q debuq-cache-quad
#COBALT -n 2
#CODALT -A EnergyFEC
# app build with GNU not Intel
module swap PrgEnv-intel PrgEnv-gnu
                                                                    Swap module for app
# Use Cray's Application Binary Independent MPI build
module swap cray-mpich cray-mpich-abi
# prints to log file the list of modules loaded (just a check)
module list
# include CRAY LD LIBRARY PATH in to the system library path
export LD LIBRARY PATH=$CRAY LD LIBRARY PATH:$LD LIBRARY PATH
# also need this additional library
export LD LIBRARY PATH=/opt/cray/wlm detect/1.2.1-6.0.4.0 22.1 gd26a3dc.ari/lib64/:$LD LIBRARY PATH
# in order to pass environment variables to a Singularity container create the variable
# with the SINGULARITYENV prefix
export SINGULARITYENV LD LIBRARY PATH=$LD LIBRARY PATH
# print to log file for debug
echo $SINGULARITYENV LD LIBRARY PATH
# this simply runs the command 'ldd /myapp/pi' inside the container and should show that
# the app is running agains the host machines Cray libmpi.so not the one inside the container
aprun -n 1 -N 1 singularity exec -B /opt:/opt:ro -B /var/opt:/var/opt:ro mpitest.img ldd /myapp/pi
# run my contianer like an application, which will run '/myapp/pi'
aprun -n 8 -N 4 singularity run -B /opt:/opt:ro -B /var/opt:/var/opt:ro mpitest.img
```

```
#!/bin/bash
#COBALT -t 30
                                   Module changes updated CRAY_LD_LIBRARY_PATH,
#COBALT -q debuq-cache-quad
#COBALT -n 2
                                   append it to local LD_LIBRARY_PATH
#COBALT -A EnergyFEC 3
                                   Also need to add addition library path.
# app build with GNU not Intel
module swap PrgEnv-intel PrgEnv-gnu
# Use Cray's Application Binary Independent MPI build
module swap cray-mpich cray-mpich-abi
# prints to log file the list of modules loaded (just a check)
module list
# include CRAY LD LIBRARY PATH in to the system library path
export LD LIBRARY PATH=$CRAY LD LIBRARY PATH:$LD LIBRARY PATH
# also need this additional library
export LD LIBRARY PATH=/opt/cray/wlm detect/1.2.1-6.0.4.0 22.1 gd26a3dc.ari/lib64/:$LD LIBRARY PATH
# in order to pass environment variables to a Singularity container create the variable
# with the SINGULARITYENV prefix
export SINGULARITYENV LD LIBRARY PATH=$LD LIBRARY PATH
# print to log file for debug
echo $SINGULARITYENV LD LIBRARY PATH
# this simply runs the command 'ldd /myapp/pi' inside the container and should show that
# the app is running agains the host machines Cray libmpi.so not the one inside the container
aprun -n 1 -N 1 singularity exec -B /opt:/opt:ro -B /var/opt:/var/opt:ro mpitest.img ldd /myapp/pi
# run my contianer like an application, which will run '/myapp/pi'
aprun -n 8 -N 4 singularity run -B /opt:/opt:ro -B /var/opt:/var/opt:ro mpitest.img
```

```
#COBALT -t 30
#COBALT -q debuq-cache-quad
#COBALT -n 2
#COBALT -A EnergyFEC 3
# app build with GNU not Intel
module swap PrgEnv-intel PrgEnv-gnu
# Use Cray's Application Binary Independent MPI build
module swap cray-mpich cray-mpich-abi
# prints to log file the list of modules loaded (just a check)
module list
# include CRAY LD LIBRARY PATH in to the system library path
export LD LIBRARY PATH=$CRAY LD LIBRARY PATH:$LD LIBRARY PATH
# also need this additional library
export LD LIBRARY PATH=/opt/cray/wlm detect/1.2.1-6.0.4.0 22.1 gd26a3dc.ari/lib64/:$LD LIBRARY PATH
# in order to pass environment variables to a Singularity container create the variable
# with the SINGULARITYENV prefix
export SINGULARITYENV LD LIBRARY PATH
                                    Run application inside singularity, aprun handles the MPI
# print to log file for debug
echo $SINGULARITYENV LD LIBRARY PATH
# this simply runs the command 'ldd /myapp/pi' inside the container and should show that
# the app is running agains the host machines Cray libmpi.so not the one inside the post machines
aprun -n 1 -N 1 singularity exec -B /opt:/opt:ro -B /var/opt:/var/opt:ro mpitest.in /ldd /myapp/pi
# run my contianer like an application, which will run '/myapp/pi'
aprun -n 8 -N 4 singularity run -B /opt:/opt:ro -B /var/opt:/var/opt:ro mpitest.img
```

#!/bin/bash

```
#!/bin/bash
#COBALT -t 30
#COBALT -q debuq-cache-quad
#COBALT -n 2
#COBALT -A EnergyFEC 3
# app build with GNU not Intel
module swap PrgEnv-intel PrgEnv-gnu
# Use Cray's Application Binary Independent MPI build
module swap cray-mpich cray-mpich-abi
# prints to log file the list of modules loaded (just a check)
module list
# include CRAY LD LIBRARY PATH in to
                                 -B /opt:/opt:ro causes Singularity to mount the host
export LD LIBRARY PATH=$CRAY LD LIBR
# also need this additional library
export LD_LIBRARY_PATH=/opt/cray/wlm '/opt' inside the container at '/opt' in read-only (ro) mode.
# in order to pass environment varia
                                 This allows the use of cray libraries that are needed to
# with the SINGULARITYENV prefix
export SINGULARITYENV LD LIBRARY PAT
                                 take advantage of Theta's unique hardware.
# print to log file for debug
echo $SINGULARITYENV LD LIBRARY PATH
# this simply runs the command 'ldd /myap /pi' inside the container and should show that
# the app is running agains the host mad es Cray libmpi.so not the one inside the container
aprun -n 1 -N 1 singularity exec -B /opt:ro -B /var/opt:/var/opt:ro mpitest.img ldd /myapp/pi
```

# run my contianer like an application, which will run '/myapp/pi'

aprun -n 8 -N 4 singularity run (-B /opt:/opt:ro )-B /var/opt:/var/opt:ro mpitest.img

#### Overview of the Workflow in Five Easy Steps!

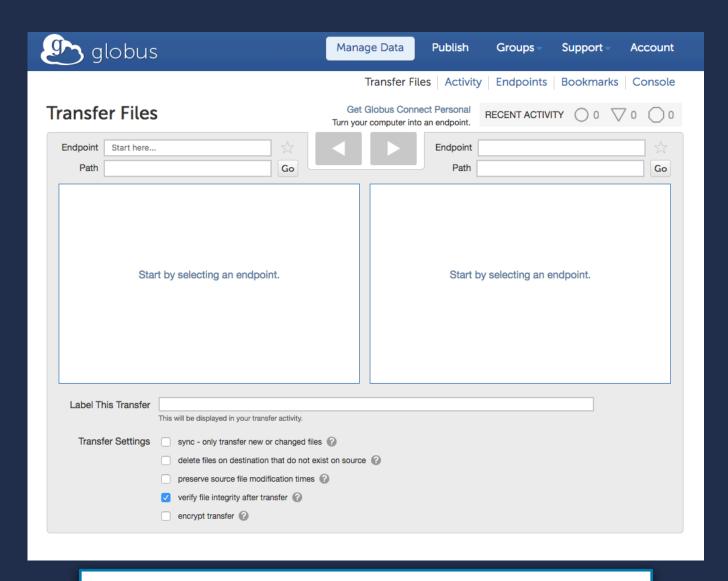
- 1. Create SingularityFile recipe in github
- 2. Link repo to Singularity Hub
- 3. Wait for build
- 4. Build on Theta
- 5. Run on Theta

Instructions for building on local machine: https://www.alcf.anl.gov/user-guides/singularity

# Built on Singularity Hub Container pi MPICH Cray MPICH Cray MPICH

#### Globus for Data Transfer

- Web Interface to transfer files between Globus Endpoints (NERSC,ALCF,OLCF,BNL,etc.)
- Login using ANL Credentials or other institutes
- Must authenticate with the myproxy server of source and destination.



https://www.globus.org/app/transfer





#### Globus for Data Transfer

• There is also a Python/Java API for doing this

https://github.com/globusonline/transfer-api-client-python

• Example Python implementation

• Provides effective transfer rates at the scale of 300MB/s between large facilities

## Theta Nodes RAM-disk (/tmp)

- Processes running on Theta compute nodes have access to /tmp
- This path maps some portion of the 192GB node DDR to a usable local filesystem
- The benefit is for low-memory applications with intermediate file-IO for non-persistent data
- Limited to 95GB
- **USE WITH CARE**: Know how much DDR your application requires, and do not write so much data to the RAM disk that your application runs out causing a crash.



#### Summary

- Data Science Group is working to support Data & Learning software stacks
- Growing support for distributed learning frameworks
- Intel/Cray support of Tensorflow through custom libraries leading to scalable Deep Learning on Theta
- Singularity installed for users
- Containers offer portability and easy distribution of software though come with complications in custom hardware environments
- Globus provides high speed data transfers between supported endpoints

